DATA SYSTEMS

GMDR-6

Ground MDR system



HEIM DATaRec® 4 GMDR



Technical Specifications

The HEIM DATaRec® 4 GMDR-6 Ground data processing systems are data acquisition, recording and playback systems. Functionally, the GMDR fully compares with a MDR mainframe and can be populated with GMDR-/MDR-type interface modules to meet the most different application requirements. A comfortable user interface is provided by two displays on the front.

GMDR-6 (SHS505-32003)

Ground MDR system

Data format IRIG 106 Chapter 10 compliant
Storage device Internal: SSD media slot (RSM/

DSM)

External: via eSATA.

Module slots 6 slots for GMDR-/MDR-type

interface modules; all modules can be exchanged by the

customer

Supported signal types for record

PCM serial

MIL 1553B buses ARINC 429 buses STANAG 3910

Serial data, asynchronous and

CAN buses Serial data, a synchronous

IEEE 1394 (Firewire)

Different bandwidth analog data,

voice

Ethernet network communication

Video (SD and HD)

Discrete

Others on request

Supported signal types for replay

PCM serial

MIL 1553B buses

Voice

Ethernet network communication

Compressed HD video Others on request

Bit rate 800 Mbit/s



Built-in interfaces

Voice

Channels 2 input single ended headset

channels

2 single ended head set monitor,

replay outputs

max. 25 kS/s selectable in steps Sampling rate

Sampling to BW ratio 2 22

High pass filter 300 Hz selectable

Resolution 8 bit / 16 bit Dynamic range 48 dB / 70 dB Input Range 1 Vrms, 1 Vpeak

> 0.1 Vrms, 0.1 Vpeak 10 mVrms, 10 mVpeak

Input coupling AC Input impedance 10 kΩ

Output Range max. 1 Vpeak

Output coupling AC

Ethernet channel

Channels 2 ports

10 / 100 / 1000 Mbit/s Ethernet Input format

bus communication

UDP broadcast, PTP (Precision **Functions**

Time Protocol: time code sync. IEEE 1588-2002 / IEEE 1588-2008), FTP server download

function, remote control

Serial

Channels 1 channel remote

1 channel GPS (NMEA)

Interface standards RS232 / RS422

Setup/Control/Remote

Interfaces USB 2.0 (Mini USB), Ethernet,

RS232, RS422

Contact Remote (CR) 6 discrete inputs CR Input level high 4 7 V- 36 V 0 V - 3.5 V CR Input level low min 25 kΩ CR Input impedance

CR Status output 6 open collector

max. 60 mA, max. 36 V(short CR Output current

circuit protected)

Time coding

Input Standard codes IRIG A, B, G, 1 pps / 10 pps, GPS

> time code, PTP (Precision Time Protocol; IEEE 1588-2002 (slave) / IEEE 1588-2008 (slave))

Input accuracy

IRIG A ±5 µs IRIG B ±20 μs IRIG G ±2 µs 1 pps / 10 pps ±0.2 µs Signal level

IRIGA, B, G 0.2 Vpp ...20 Vpp

GPS (NMEA) RS232 / RS422 standard

1 pps / 10 pps

Input impedance IRIG A, B, G: 25 kΩ

Output

Standard codes IRIG A, B, G, 1 pps / 10 pps; GPS

> replay as RS232, PTP (Precision Time Protocol; IEEE 1588-2002 time master version 1 / IEEE 1588-2008 time master version 2)

Output accuracy $2 \times 10^{-5} s$ (standard)

2 Vpp on 75 Ω (IRIG A, B, G), Signal level

RS232 (NMEA), TTL (1 pps /

10 pps)

Output impedance 75 Ω (IRIG A, B, G)

Synchronization 1 pps / 10 pps output with 1 µs

accuracy

Build-in GPS receiver (optional)

Receiver type 50 channels

GPS L1 frequency C/A code

Galileo open service L1

frequency

Max. speed < 600 m/s

Max. navigation update rate 4 Hz Velocity accuracy 0.1 m/s

Heading accuracy 0.5 degrees

Dynamics < 4 q

Horizontal position < 2.5 m autonomous

Accuracy > 2.0 m SBAS

Power for active antenna 5.0 V Real time clock (RTC) time accuracy

Power on state ±1 ppm (< +25 °C)

±4 ppm

10 ppb (with optional High

Precision Oscillator)

Power off state ±2 ppm (0 ...+25 °C)

±4 ppm

Additional Functions

Data integrity The built-in power supply system

provides for a clean shut down if power is lost during recording, avoiding data corruption.

General

Supply voltage

Nominal input voltage 100 ...240 V AC
Input voltage range 90 ...264 V AC
Input voltage frequency 48 ...62 Hz
Input current 1.0 A max.

Power consumption

GMDR-6 30W without signal modules and

without storage media

Connectors

Power AC power

Time, voice, synch HD-D-Sub 26 pin female Remote HD-D-Sub 26 pin female

GPS antenna SMA (with optional GPS receiver)

eSATA (front) Host (e. g. for external storage

media)

Mini USB (front, for setup/control only)

USB 2.0

LAN RJ45

Communication interfaces

Displays 2 x LCD color active matrix; Status indicators 3 x LED, for system, time and

media status

Buttons 9 buttons for basic functions and

menu navigation on the right

hand display

Dimensions 482.6 x 44.4 x 342.5 mm

(w x h x d)

Weight 5 kg

Environmental specifications

Temperature in accordance with standard IEC

operating -15°C ... +55°C storage -20°C ... +70°C

DIN EN60068-2-14Nb

Humidity 0 ... 93% relative, non-

condensing

EMC EU-Directive 2014/30/EU (EMV)

IEC DIN EN61000-6-4
IEC DIN EN61326-1
IEC DIN EN61000-6-2
IEC DIN EN61000-4-3

DIN EN55011

Notes

Performance varies depending on installation environment. The values shown were measured using an appropriately designed test system with a default setup under nominal conditions of temperature, voltage, etc. Performance is significantly influenced by storage medium type, signal module configuration, power supplies and cabling.

Features and capabilities of the MDR product line as well as the range of its pertaining items are continuously evolving. Before being able to utilize new features, functions or modules, the firmware of the MDR system has to be updated to the latest firmware version.

Take ESD precautions when handling MDR modules. Always ensure to use only cables with the correct pin out for the interface module! The use of cables with wrong pin assignment may result in damage to connected hardware.

Definitions

Specifications with limiting symbols (<, >, \leq , \geq , \pm , min, max, etc.) or a domain (...) represent performance within a range of values. Specifications named as "typical" represent performance met by approximately more than 80% of the specification basis (channels, produced devices, ...). Specifications without limits are nominal values or values within standard tolerances (e. g. dimensions).

Safran Data Systems GmbH

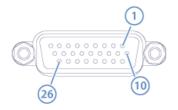
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Connector Pin out

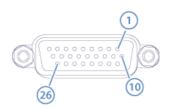
Time/voice/synch (D-Sub type, HD 26-pin female)

Pin	Description	
	IRIG interface	
8	IRIG analog time code input	
7	IRIG analog time code output	
9	IRIG analog signal ground	
	PPS interface	
17	1/10 PPS input	
16	1/10 PPS output	
18	1/10 PPS signal ground	
	Serial GPS (NMEA) interface	
22	GPS RS422 serial data receiver input -, symmetrical signal	
21	GPS RS422 serial data receiver input +, symmetrical signal	
20	GPS RS422 transmitter output +	
19	GPS RS422 transmitter output -	
25	GPS RS232 receiver input	
24	GPS RS232 transmitter output	
23	GPS RS232/RS422 common signal ground	
	Voice interface	
2	Voice line input 1	
3	Voice line input 2	
1	Voice line input ground	
11	Voice line output 1	
12	Voice line output 2	
10	Voice line output ground	
	Synchronisation interface	
15	Synchronous 1 I/O+	
6	Synchronous 1 I/O-	
13	Synchronous 2 I/O+	
4	Synchronous 2 I/O-	
5	Synchronous configuration input	
14	Synchronous common ground	
26	Common cable shield (case)	



Remote/media (D-Sub type, HD 26-pin female)

Pin	Description
	Power supply interface
10	Power supply output (24 V DC / 400 mA)
1	Power supply ground (isolated from signal ground)
19	Power supply shield (case)
	Serial remote interface
20	RS422 receive input pair +
21	RS422 receive input pair -
11	RS422 transmit output pair +
12	RS422 transmit output pair -
2	RS232 receive input
3	RS232 transmit output
13	RS232/RS422 common signal ground
4	RS232/RS422 common cable shield (case)
	Contact remote interface
5	C-REM input 1 (record)
6	C-REM input 2 (erase)
7	C-REM input 3 (declassify)
8	C-REM input 4 (self-test)
16	C-REM input 5 (enable)
17	C-REM input 6 (event)
14	C-REM open collector output 1 (record status)
15	C-REM open collector output 2 (erase status)
22	C-REM open collector output 3 (declassify status)
23	C-REM open collector output 4 (self-test status)
24	C-REM open collector output 5 (critical error status)
25	C-REM open collector output 6
18	C-REM Power output +5 V DC / 1 A
9	C-REM I/O common signal ground
26	C-REM I/O cable shield (case)

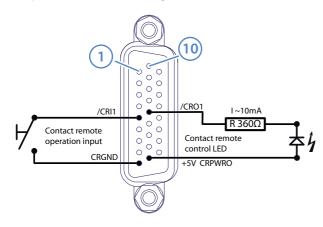


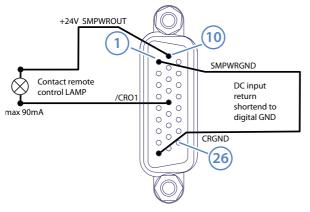
Specification of the contact remote interface

All outputs are open drain signals, active low. For example when record is running, the record output will be pulled to ground with a current limit of 90 mA. When record is not running the pin is floating. An external pullup resister should be provided with a maximum voltage of 50V.

The input pins are also low active and should be pulled to GND to activate them. When left open, an internal current source (0.5 mA limit) will pull the pins to 5.0 V. The function will be activated if the corresponding pin is pulled below 3.0 V. This should be done using a switch, relay, open drain FET or similar. The inputs can also tolerate higher voltages of up to 35 V (direct connection to 28 V aircraft power is possible).

Example for contact remote wiring





Optional: GPS (SMA female)

Pin	Description
1	Signal input (inner contact)
2	Signal ground (outer contact)